

#### The partners:







#### **Funding:**



**EUROPÄISCHE UNION** Investition in unsere Zukunft
Europäischer Fonds für regionale Entwicklung



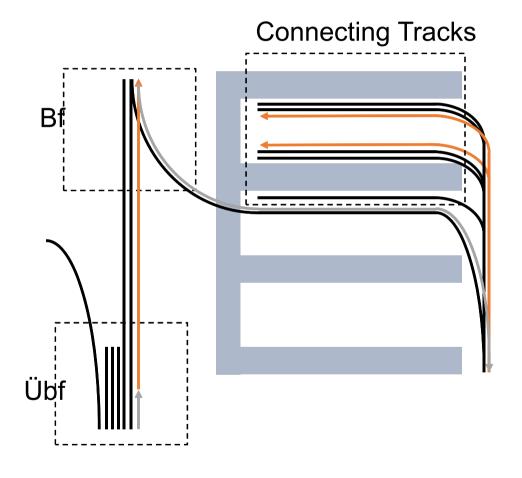
#### **EFRE.NRW**

Investitionen in Wachstum und Beschäftigung

SAMIRA-Projekt is being funded under EFRE-0801689

## **Typical Operation in Harbour Area**





pulled shunting drive pushed shunting drive

Multiple
Change of the
Directions
required



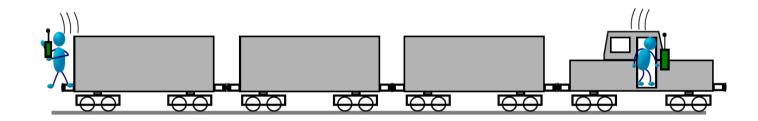




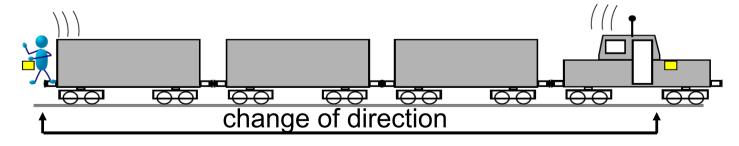




## Either operated by two people ....



## .... or by remote control









## **Problem / Initial Situation**



- The cost of last mile services at terminals and junctions is too high compared with other transport modes
- For long trains the use of an additional shunting attendant is necessary, as the range of an existing radio remote control is not sufficient,
- In the upcoming digitalisation, freight wagons will also be equipped with the corresponding technology, whereby the wagon rental companies will record the corresponding data on vehicle conditions,
- Demographic change, shortage of skilled workers and cost pressure therefore require new, - i.e. digital - solutions to increase efficiency.









## **Technological Solution**

- As an alternative for having a shunting attendant or a locomotive driver at the end of the train, an electronic system is used to collect and remotely transmit the necessary information directly to the driver at the locomotive.
- An appropriate interface must be developed and installed on the locomotive to receive all data, process them accordingly and provide it reliably to the locomotive driver.
- ➤ The aim of the SAMIRA project is to create the technical and organisational conditions for the production and practical use of such a system.





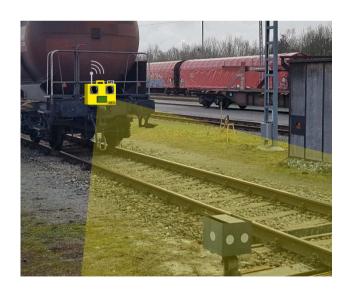


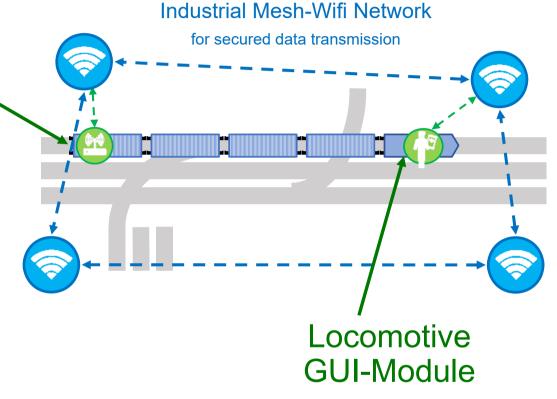
### **Solution: Shunting Assistant**



#### Portable Sensor Module

- Camera
- Radar / LIDAR
- Track-selected position
- Transmission via mesh-wifi to locomotive











## **Extended Concept SAMIRA**



# **Dataflow**: Shunting Assistant Stationary track monitoring

## **Components**:

**Control Centre** 

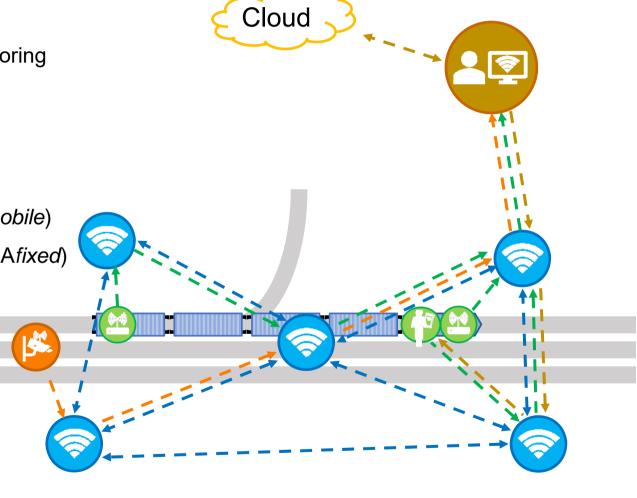
Mesh nodes

Mobile Unit (SAMIRA*mobile*)

Stationary Unit (SAMIRA fixed)

Edge Server

( GUI



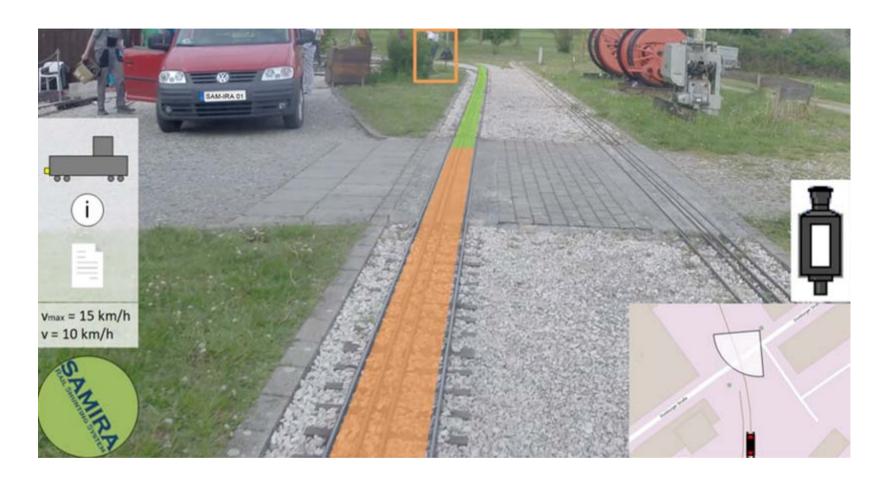






## **Display with Augmented Reality**











## **Technical Requirements**



- Loco driver is always in a safe and comfortable environment
- Infrastructure components are remotely controlled or operation must be organized accordingly.
- Real time data transmission must be guaranteed.
- Precise, track-selective positioning must be guaranteed while driving.
- A clear assignment between SAMIRA mobile device and receiver in loco's driver cab is required.
- Automatic change of camera image when changing direction
- Train length and position information must be recorded and communicated
- Locating is necessary as a preventive measure against loss of any mobile device







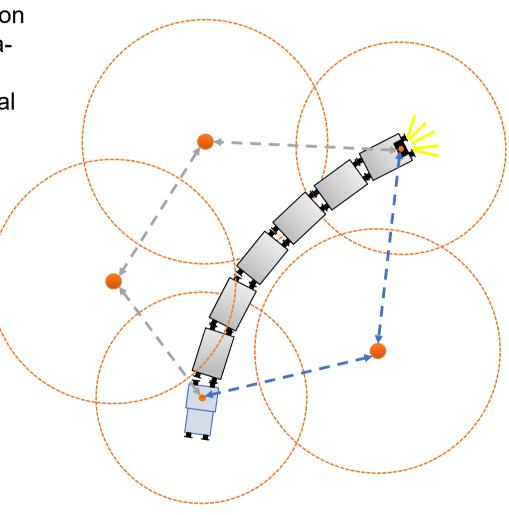
#### Data Transmission via Wireless Mesh Network (WMN)



To ensure seamless data transmission a radio network with a sufficient data-transmission rate required.

A first approach is a secure, industrial wireless mesh network

- Fixed transmission nodes
- Mobile transmission nodes
- Internet connection possible
- Redundancy
- Dynamic Routing







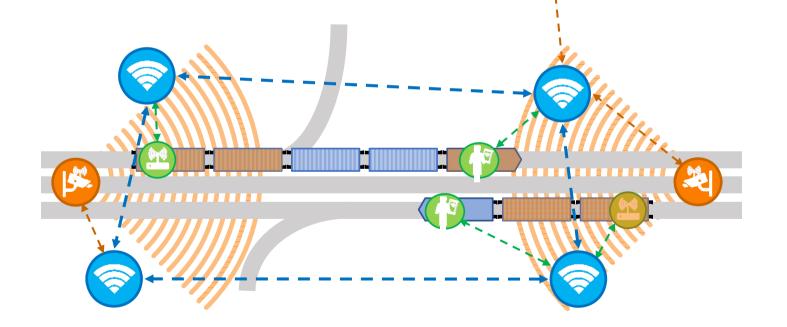


## **Track-selective Positioning**

SAMIRA RAIL SHUNTING SYSTEM

- Accurate train information system
- Train Management
- two independent systems
- Requirements for (partially) autonomous driving





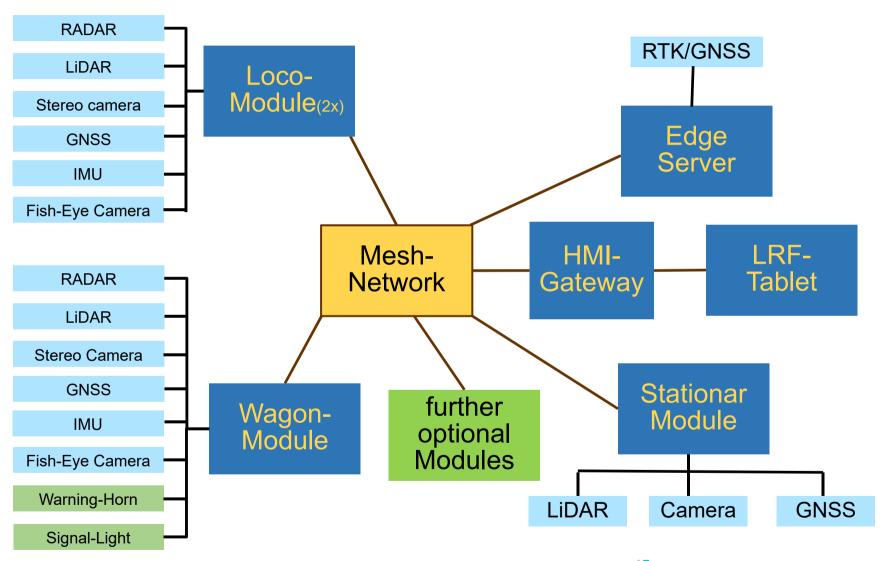






## **SAMIRA System Architecture**





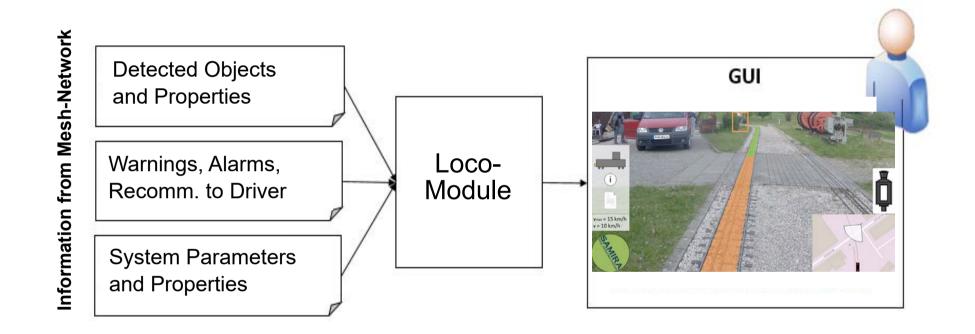






## **Generation of Display Information**





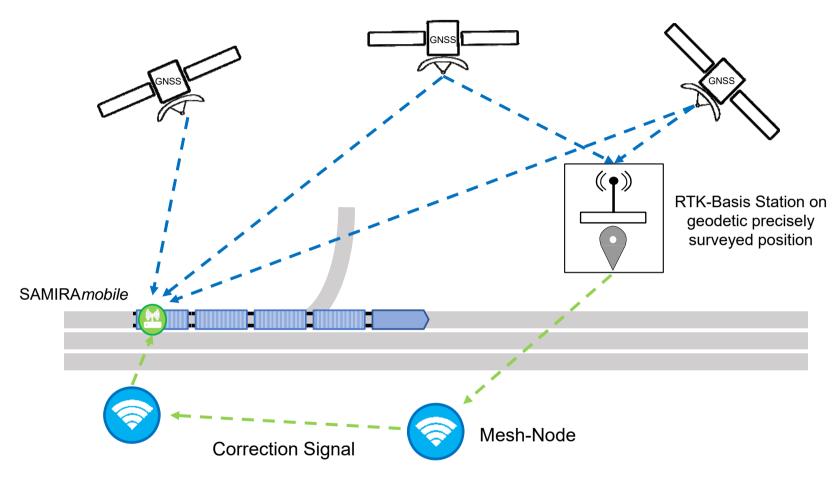






## **Concept RTK**





RTK = Real Time Kinematic



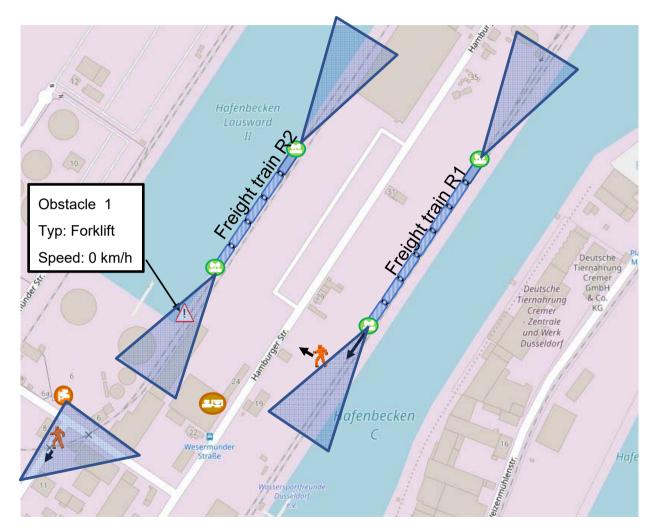




## **Digital Map**



- Mobile Device
- Stationary Device
  Edge Server
- Pedestrians
- Obstacle
- Freight train
- → Velocity vector
- Detection area











#### **SAMIRA** provides manifold advantages:

- ➤ The shunting attendant is no longer required and can now be better used as an additional shunting driver on the locomotive
- SAMIRA increases safety in railway operations, especially at night, in fog, snowfall or heavy rain
- SAMIRA supports to reduce (rear-end) accidents and so reduction of downtimes, repair costs and insurance premiums
- The captured data and (augmented) live images including position information can be displayed with all (mobile) components integrated into the mesh network, e.g. control centre, signal box, terminals, etc.
- ➤ SAMIRA is already creating the basic structure for further digitization in the railway sector (i.e. Logistics 4.0, IoT).







#### **SAMIRA: a Modular System**



#### SAMIRA can be configured modularly and adapted to your requirements:

#### a) SAMIRA basic system

- > Sensors mobile module on freight wagon and display in driver's cab
- Basic system RTUS shunting with technically supported tip

#### b) SAMIRA train system

- Additional sensors permanently installed in the locomotive on one side
- for locomotives with one or two cabs

#### c) SAMIRA fully equipped

- Additional sensors permanently installed in locomotive on both sides
- for locomotives with one or two cabs

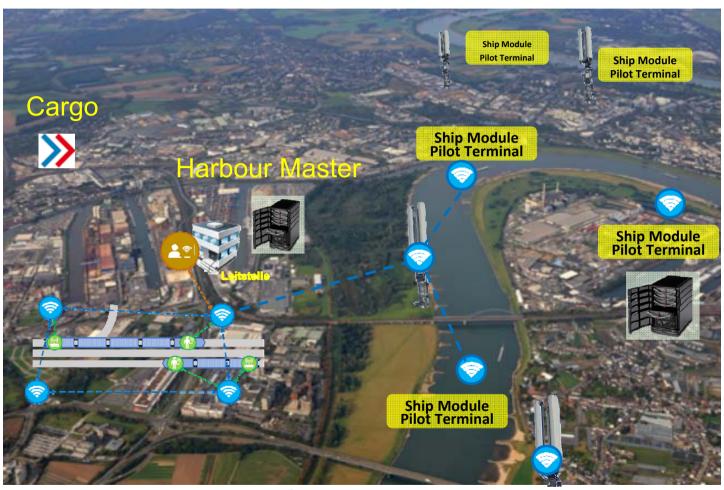






## **SAMIRA** in the intermodal logistic strategy





Luftaufnahme 2017 von http://www.nd-haefen.de/











## Thank you!

#### **Contact:**

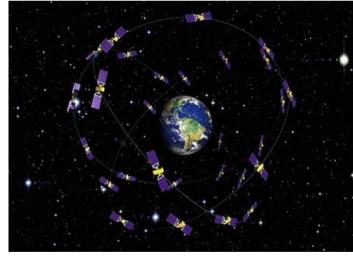
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Das Europäische Galileo System

Grafik: esa





